Aggregating Strategic Information

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June 2024 Cowles Annual Economic Theory Conference 2024

Aggregating Information

- Decision-makers often rely on information from multiple sources
	- 1. Board relies on reports of multiple divisions
	- 2. CB rate decisions communicate views of many board members
	- 3. Online trade and review aggregation: Yelp, IMDb, Goodreads

Aggregating Information

- Decision-makers often rely on information from multiple sources
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- Common issue: conflicts of interest & strategic manipulation

- Is there a way for an aggregator to overcome this strategic manipulation while being informative?
- What are the properties of optimal mechanism?
- How does this mechanism depend on
	- the level of "conflict"
	- the number of senders

Literature

Multi-sender/issue cheap talk: Austen-Smith (1993), Krishna & Morgan (2001), Battaglini (2002, 2004), Ambrus et al. (2013), Meyer et al. (2019), Lipnowski and Ravid (2020), Antic et al (2023).

Mediation/mechanism design in communication games: Wolinsky (2002), Krishna & Morgan (2008), Goltsman et al. (2009), Salamanca (2020), Jann & Schottmüller (2023).

Mechanism Design without transfers: Börgers $\&$ Postl (2009), Gershkov et al. (2017) , Li et al (2017) , Guo & Hörner (2018) , Kattwinkel, et al (2022), Kattwinkel & Winter (in progress)

Incentives in information design: Onuchic and Ray (2022), Boleslavski and Kim (2023), Saeedi and Shourideh (2023)

This paper:

Optimal multi-sender communication mechanisms without transfers or cross-checking.

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- *n* senders each with iid type $s_i \sim F[-1, 1]$, • where $\mathbf{s} = (s_i)_{i=1}^n$.
- A receiver with binary action $a \in \{0, 1\}.$
- Payoff relevant state variable $\omega = \frac{\sum_{i=1}^{n} s_i}{n}$
- Receiver Payoff: $a\omega$.
- Senders' Payoff: $a(\omega + b)$ with $b > 0$.
	- \circ Biased toward $a = 1$

Two Sender Case

Two Sender Case, Receiver Optimal Action

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Two Sender Case, Senders Optimal Action

Disagreement Region

- Mediator with commitment, e.g., a review aggregator
- Commits to a mechanism $\sigma : [-1,1]^n \to \Delta \{0,1\}.$

◦ Myerson (1982, 1986): WLOG, direct mechanisms

- Each sender reports type $s_i \in [-1,1]$ to the mediator
- The mediator recommends action $\tilde{a} = 1$ with probability equal to $\sigma(\mathbf{s}=(s_i)_{i=1}^n).$
- After observing \tilde{a} , receiver chooses $a \in \{0,1\}$ and payoffs are realized.

Mediator Problem, Maximizing Receiver Payoff

$$
\max_{\sigma} \mathbb{E}\left[\sigma(\mathbf{s})\omega\right]
$$

Subject to

$$
s_{i} \in \arg\max_{\tilde{s}} \mathbb{E}\left[\sigma(\tilde{s}, \mathbf{s}_{-i})\left(\omega + b\right)\right]
$$
 (IC)

$$
\mathbb{E}_{\sigma}\left[\omega \mid \tilde{a}\right](2\tilde{a}-1) \ge 0\tag{OB}
$$

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Small Bias: Sender Preferred Mechanism

Theorem. The optimal mechanism induces the senders' first best allocation if

$$
1 - bn\left(1 - \frac{f'(x)}{f(x)}(1 - x)\right) \ge 0, \ \forall x \in [-1, 1]
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- Sender first best is optimal when
	- bias is small relative to number of senders

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- f'/f imposes conditions on density (more on it later)

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Two main steps:

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	- $\circ~$ Standard methods do not work: non-empty interior in L^∞
	- Use Mitter (2008), perturbing incentive constraints are bounded by a linear function
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Two main steps:

- Strong duality holds
	- $\circ~$ Standard methods do not work: non-empty interior in L^∞
	- Use Mitter (2008), perturbing incentive constraints are bounded by a linear function
		- As in Kleiner & Manelli (2019) and Kushnir & Shourideh (2024)
- Constructing Lagrange Multipliers and proving that using those the only solution is seller preferred allocation
	- After many steps of algebra, we get to a term that is in form of

 $\sigma(s)(\omega + b)A$

- \circ The assumptions ensures that A is positive.
- \circ Then to maximize objective set σ
	- Equal to 1, if $(\omega + b) > 0$
	- Equal to 0, if $(\omega + b) < 0$

Corollary. If the distributions of types are uniform, then the optimal mechanism induced by the senders' first best allocation if and only if

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$$

- The higher the number of senders, the smaller the bias that induces senders first best
- Each sender has smaller share of the total information

• What prevents us from setting $\sigma = 0$ in the disagreement region?

- Let's assume that we set $\sigma = 0$ in disagreement region as above.
- To make the IC for these types hold, should make higher types worse off.

- Next step, more valuable ω , we can make the deviation smaller
- But we need to keep going!

• We need to keep making higher levels of s worse off even in the agreement region.

• Keep going until ...

• We get to $s_1, s_2 = 1$

- For the receiver, in the case of uniform and $b = 1/2$
	- \circ The benefit (green) = The cost (red)

- For the receiver, in the case of uniform and $b < 1/2$
	- The benefit (green) < The cost (red)

- $\bullet\,$ For the receiver, in the case of uniform and $b>1/2$
	- \circ The benefit (green) $>$ The cost (red)

- At $b = 1/2$ above non-monotone mechanism satisfies IC
- Gives receiver the same payoff as sender best allocation

• Condition (1) :

$$
1-bn\left(1-\frac{f'(x)}{f(x)}(1-x)\right)\geq 0
$$

- Density cannot be declining too fast.
- Somewhat similar to increasing virtual values in Myerson (81).

Intuition: Condition (1)

• Our condition ensures that there is no big mass in the disagreement region

Proposition. There exists a $\overline{b} \in \left[\frac{1}{n}, 1\right)$ such that the optimal mechanism is non-monotonic for all $b > \overline{b}$.

Large bias: Non-monotone Mechanism

Proof Outline

• We first show that all IC and monotone mechanisms have one of the following two forms or their combinations.

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- Construct an upper bound on $\mathbb{E}_{\sigma}u^{R}$ from monotonic σ
- Show that it converges to zero as $b \to 1$.
- Show there always exists an informative non-monotonic mechanism.

Optimal Non-monotone Mechanisms!

$$
b = .6, s \sim U [-1, 1]
$$

• Blue area:
$$
\sigma = 1
$$
, the rest, $\sigma = 0$

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- Assume that the mediator restricts itself to a *simpler* mechanisms
- The mediator asks the senders if their signal was positive or negative (Thumbs up/Thumbs down)
- Then implements a mechanism as a function of number of positive signals: $\sigma(k)$
- This will greatly simplify IC's and the number of parameters for σ
- Let's assume that the distribution of signals are uniform for the presentation (Not necessary)

• The problem of the mediator and IC will become maximizing the following:

$$
V_n(\sigma(k)) = \sum_{k=0}^n \binom{n}{k} \sigma(k) \mathbb{E}(\omega|k)
$$
 (2)

• Subject to the IC for $s = 0$:

$$
\sum_{k=0}^{n-1} {n-1 \choose k} (\sigma(k+1) - \sigma(k)) \mathbb{E}(\omega + b|s = 0, k) = 0
$$

• Monotonicity and Obedience

• We show that the optimal σ has one of the following two forms:

Monotone Mechanism

• We show that the optimal σ has one of the following two forms:

- For low levels of b the monotone mechanism will be optimal
	- This is the closest approximation to sender best
- For high levels of b the non-monotone will be optimal
	- \circ The switch happens exactly at $b = 1/n$
	- Similar to the non-monotone mechanism for two sender.

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Parallel to the Delegation Problem

- In our problem we assume that the mediator gets information from multiple sources
- What if the mediator, has its own private signal and wants to elicit only one other source
	- \circ s₂ is directly observed
	- \circ Elicit information from sender 1: s_1

Parallel to the Delegation Problem

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- What if the mediator, has its own private signal and wants to elicit only one other source
	- \circ s₂ is directly observed
	- \circ Elicit information from sender 1: s_1
- The designer's problem is

$$
\max \mathbb{E}[\frac{(s_1+s_2)}{2}\sigma(s_1,s_2)]
$$

Subject to

$$
s_1 \in \arg\max_{\tilde{s}} \mathbb{E}\left[\sigma(\tilde{s}, s_2) \left(\frac{(s_1 + s_2)}{2} + b\right)\right]
$$
 (IC)

Parallel to the Delegation

Theorem. Assuming inverse hazard rate, $\frac{1-F}{f}$, is non-increasing, the following mechanism maximizes the receiver's expected payoff:

1. If $1 + \mathbb{E}[s] < 2b$:

$$
\sigma^{\star}(s_1, s_2) = \begin{cases} 1, & \text{if } s_2 \ge -\mathbb{E}[s_1] \\ 0, & \text{otherwise.} \end{cases}
$$

2. If
$$
1 + \mathbb{E}[s] \ge 2b
$$
:
\n
$$
\sigma^*(s_1, s_2) = \begin{cases}\n1, & \text{if } s_2 \ge -\bar{s}_1 - 2b \text{ and } s_1 \ge -s_2 - 2b \\
0, & \text{otherwise.} \n\end{cases}
$$

where $\bar{s}_1 \in (-1, 1)$ is the unique solution to $\mathbb{E}[s_1 | s_1 \ge s_1'] = s_1' + 2b.$

Parallel to the Delegation - Low Bias

Parallel to the Delegation \equiv

• High bias:

- Ignore the signal from sender 1
- Low bias:
	- If own signal is too low: recommend action 0
	- Otherwise, privately let sender 1 know your signal and delegate

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• High bias:

- Ignore the signal from sender 1
- Low bias:
	- If own signal is too low: recommend action 0
	- Otherwise, privately let sender 1 know your signal and delegate
- In this case, we do not have a non-monotone mechanism.
- Non-monotonicity is a feature of incentivizing multiple senders at the same time
- One sender case: same as interval delegation:
	- Amador, Werning, and Angeletos (2006), Alonso and Matouschek (2008), Amador and Bagwell (2013), Halac and Yared (2014, 2018, 2020, 2022, ...?), ...
- When the bias and number of senders are small:
	- Sender best is optimal
	- Mediator can implement this by allowing the senders to talk freely and propose the action to reciever
- High bias or large number of sender
	- The mediator can improve the outcome for the receiver by implementing a non-monotone mechanism
	- Amazon retracting high ratings from time to time

Thank you!

Monotonic versus Nonmonotonic Mechanisms [Back](#page-20-0)

We say a mechanism is (ex post) monotonic IFF

$$
\sigma(\tilde{s}, \mathbf{s}_{-i}) - \sigma(s_i, \mathbf{s}_{-i}) \ge 0
$$
 for all $\tilde{s} \ge s_i$, $\mathbf{s}_{-i} \in [-1, 1]^{n-1}$

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$$

This is distinct from interim monotonicity, which is always required by IC:

$$
\mathbb{E}[\sigma(\tilde{s}, \mathbf{s}_{-i})]
$$
 is non-decreasing in \tilde{s} .